

# **Integrated modelling systems**

**(Simplified and generalized view)**

*Serge Ivanov, OSENU*

**?**

**Model Simulation = True Atmospheric State**

?

## Model Simulation = True Atmospheric State



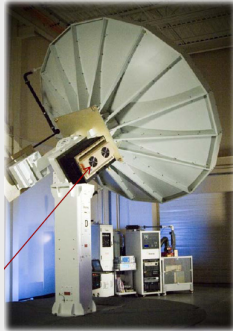
- Dynamical block: underestimation of synoptic activity and blocking; polarward shifting of storm-track, ...
- Physical block: latent heat flux over the ocean; stratiform cloudiness; gravity waves over orography; ...

Ingleby, 2001; Jung, 2005; Klinker et al, 1998; Montani et al, 1999; Reynolds et al, 2005; Simmons and Hollingsworth, 2002; Zhou et al, 1996;

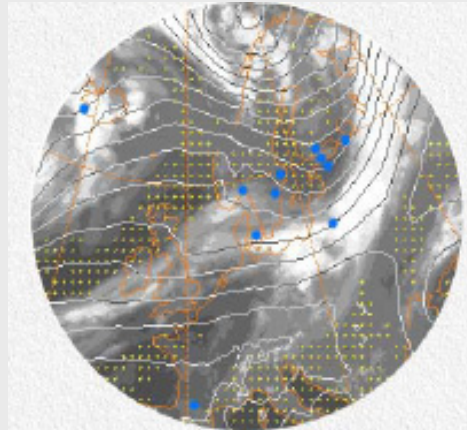
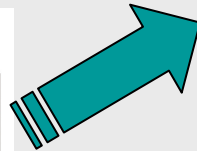
# Progress in forecasting



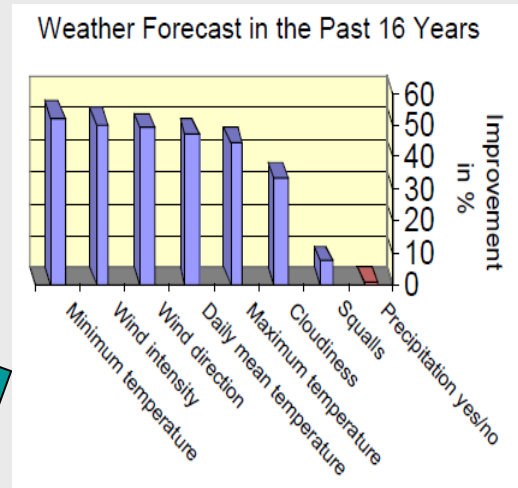
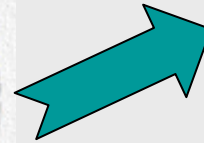
Remote sensing



Computer facilities



Model developments:  
 Dynamical core,  
 Physics,  
 DA  
 Resolution



*Hense et al, 2003*

**Progress !?**

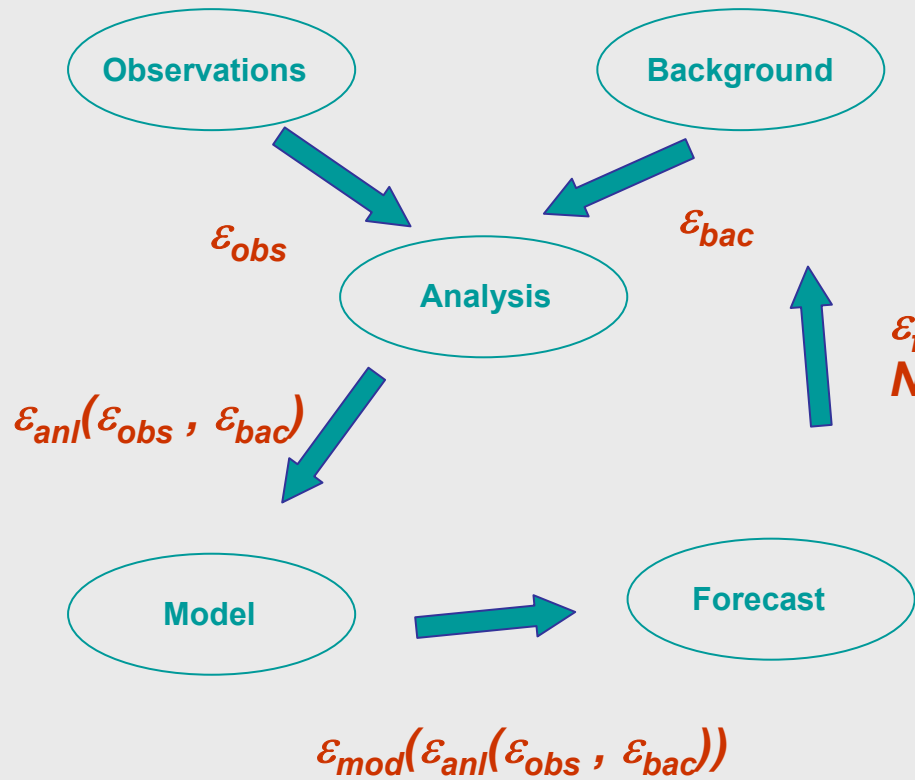
# Reasons

- Imperfect knowledge about phys, chem, met processes
- Assumptions in meteo description by differential and integral equations
- Approximation of differential equations by finite differences
- Errors and uncertainties in initial conditions
- Sensitivity to the above stuff in IC
- Do you think so or do you know that ?
- Geostrophic, hydrostatic, Boussinesq, ...
- $dx/dt \rightarrow \lim (\Delta x / \Delta t) , \Delta t \neq 0$
- Accuracy of observation systems is limited + non-unique transfer functions for remote sensing + representativeness error
- Remove the noise and stress the signal, but how do separate them?

Last but not least: Predictability of the atmosphere

? Lyapunov (in-)stability

# Error flow



Forecast – Truth = Error  
! - ? = ?  
Direct estimating of the  
error  
is not available

$\epsilon_{for}(\epsilon_{mod}, \epsilon_{ani}, \epsilon_{obs}, \epsilon_{bac})$   
*Non-separable components*

Both the FORECAST and  
FORECAST ERROR  
are important

## Model stages

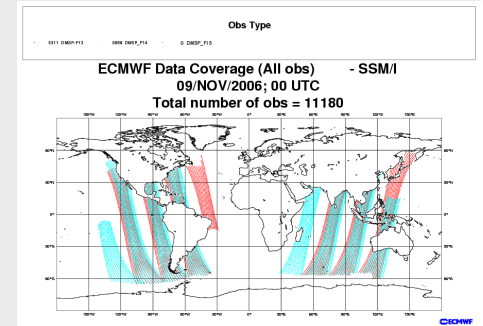
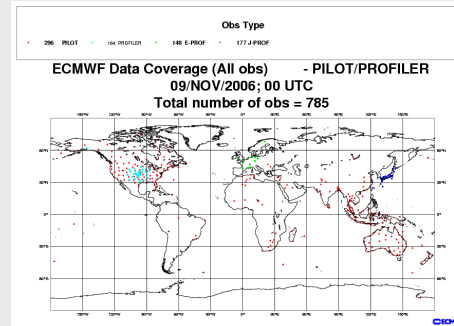
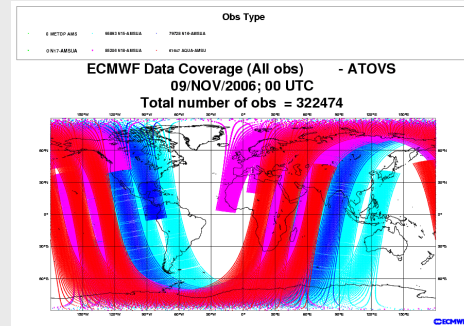
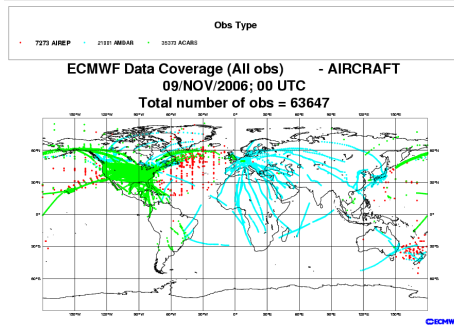
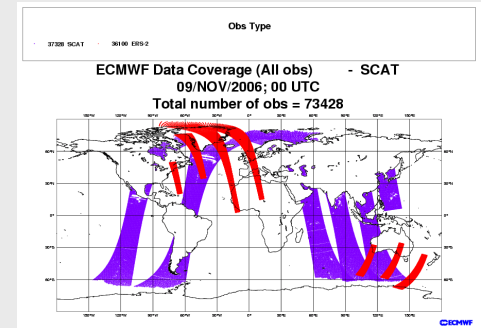
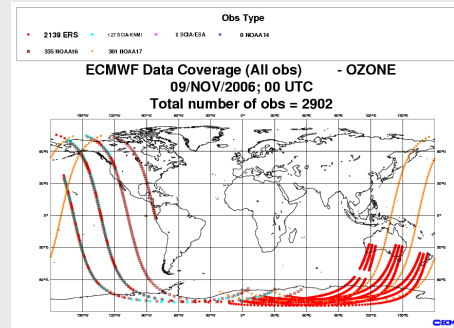
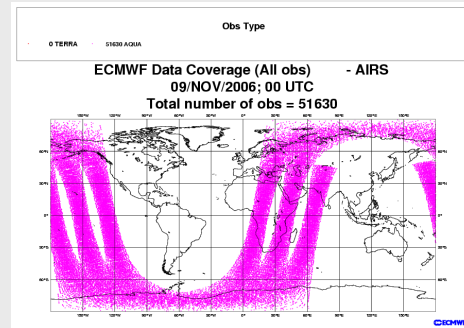
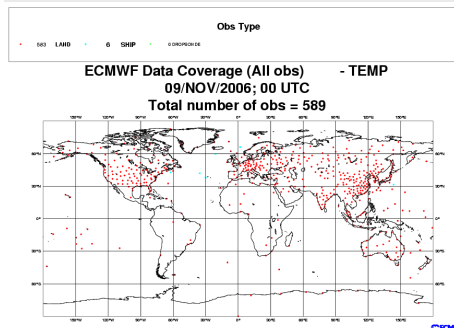
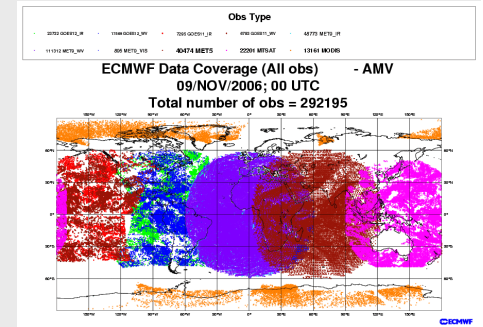
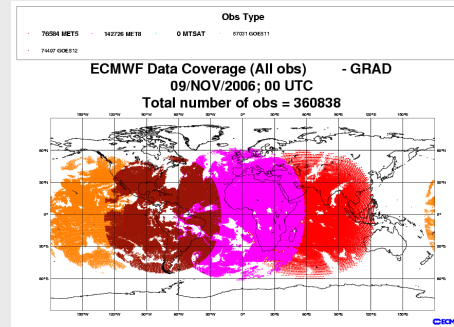
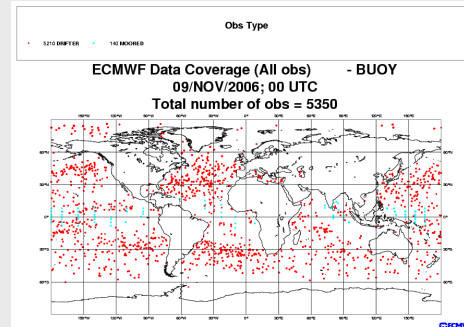
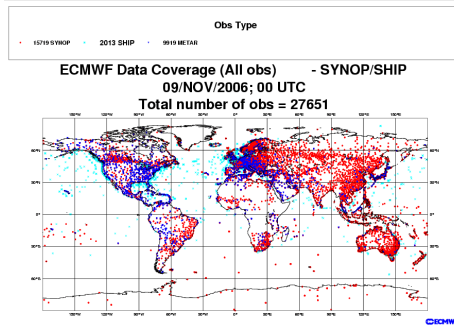
- **Observation (gathering, controlling, screening, ...)**
- **Data Assimilation – finding a statistically optimal atmospheric state (nudging, OI, nD-var, KF, ...)**
- **Model Initialization – creating IC satisfying physical consistency (L(N)NMI, DF, diabatic, ...)**
- **Dynamical Core – numerical solver (Grid, Spectral, FE, Euler, Lagrange, ...)**
- **Physical Parameterization – taking into account unresolved scales (Microphysics, Convection, PBL, Radiation, Orography Drag, Diffusion, ...)**
- **Post-Processing – comfortable issue for users (model levels => mandatory and non-mandatory surfaces, 2m temp, 10m wind, ... , visualization, ...)**

## Model stages

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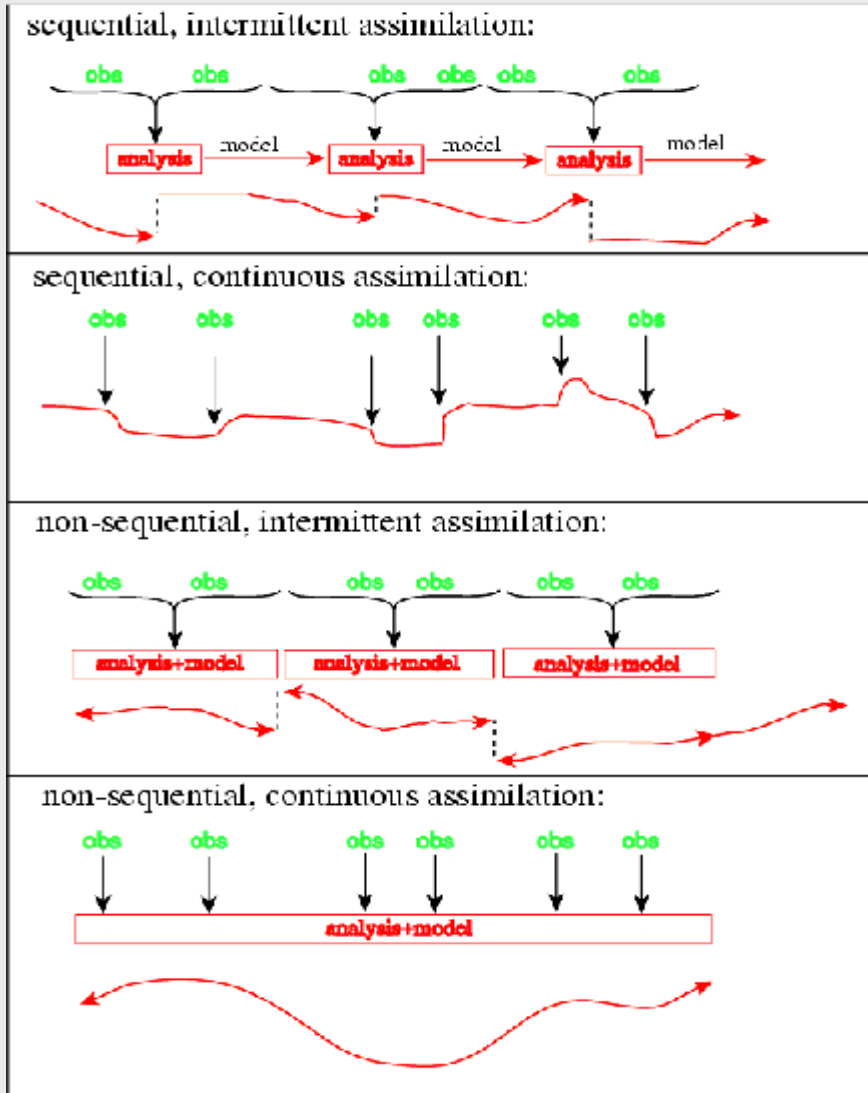
# Observation types



## Model stages

- **Observation** (gathering, controlling, screening, ...)
- **Data Assimilation** – finding a statistically optimal atmospheric state (nudging, OI, nD-var, KF, ...)
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# Data assimilation



$$J(\delta x) = J^b(\delta x) + J^o(\delta x)$$

Background Term

Observation Term

(Courtier et al, 1994)

(Holm, 2003, ECMWF)

## Model stages

- **Observation (gathering, controlling, screening, ...)**
- **Data Assimilation – finding a statistically optimal atmospheric state (nudging, OI, nD-var, KF, ...)**
- **Model Initialization – creating IC satisfying physical consistency (L(N)NMI, DF, diabatic, ...) but also allowing perturbations of various nature**
- **Dynamical Core – numerical solver (Grid, Spectral, FE, Euler, Lagrange, ...)**
- **Physical Parameterization – taking into account unresolved scales (Microphysics, Convection, PBL, Radiation, Orography Drag, Diffusion, ...)**
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# Model Initialization

$$J(\delta x) = J^b(\delta x) + J^o(\delta x) + J^c(\delta x)$$



**Physical consistency in the model  
(compatibility of the mass, wind,  
temp, ..., fields)  
controlling high-frequency modes**

**Latent Heat Nudging – is a  
sophisticated scheme used for  
nowcasting**

**LNMI, NNMI is good for a global  
domain, but restricted for a  
regional domain and meso-scale  
process initialization**

**DF is preferable for regional  
domains. It dumps high-  
frequency perturbations within a  
domain as well as on lateral and  
top boundaries**

## Model stages

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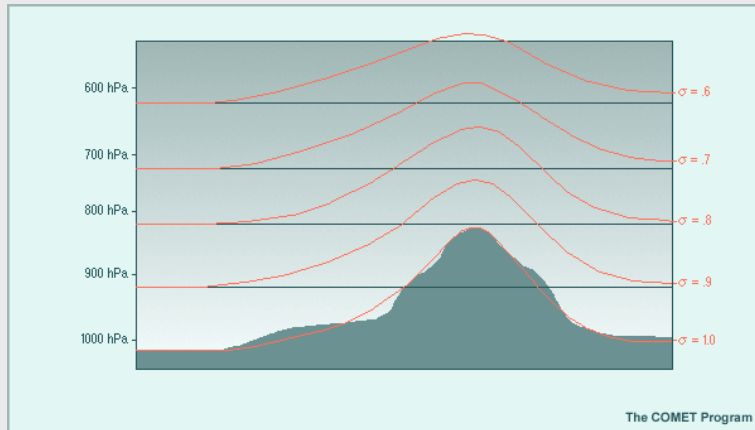
# **Dynamical Core**

**See Eigil Kaas' lectures**

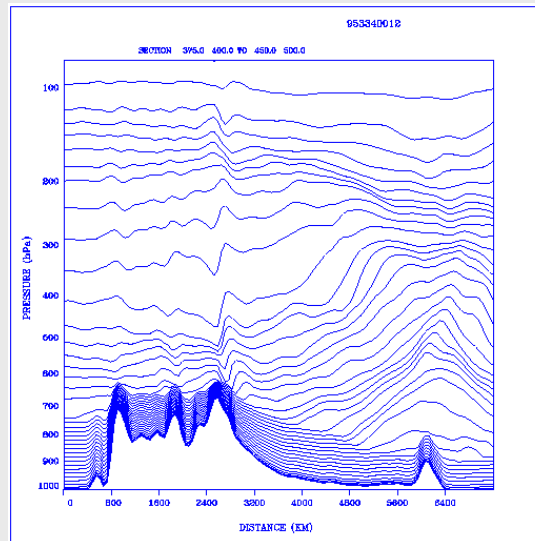
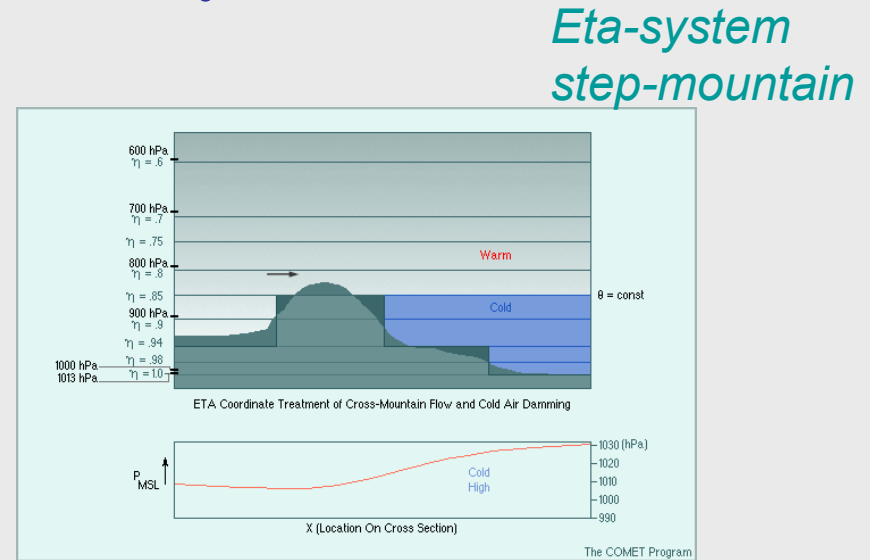
**+**

**vertical coordinate systems**

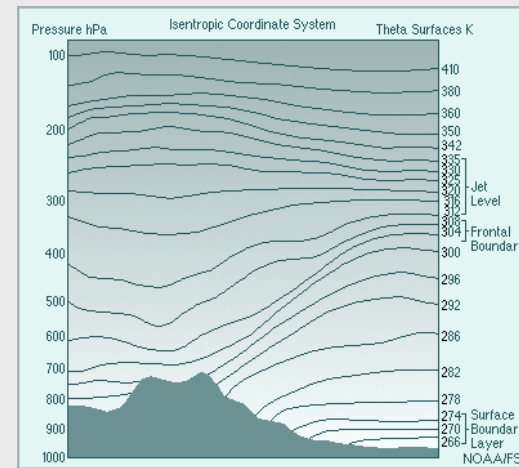
# Vertical Coordinate Systems



$\sigma$ -system  
terrain-following



Hybrid system



$\theta$ -system



# Vertical Coordinate Systems

## System

## Advantages

## Drawbacks

<b><i>Sigma</i></b>	<p>Accounting terrain Different step in PBL and upper layers No crossing between CS and TS</p>	<p>Different slope values over complex terrain =&gt; error in PG, advection, lateral diffusion =&gt; noise generation Increased horizontal resolution =&gt; Higher slope of CS Requires an additional term to compute PG Difficulties in computations on the lee side of terrain Distorted coastline due to the smooth orography requirement</p>
<b><i>(Phillips, 1957)</i></b>		
<b><i>Eta</i></b>	<p>The reference surface is on the sea surface Simple computations and transformation due to the flat basis at every box Realistic simulations over steep orography and on the mountain lee side Better precipitation forecast</p>	<p>Difficulty for detailed description of PBL on a large domain The low slope is approximated by one step Requires to set up interior boundaries on vertical walls Not allowing vectorization Requires equal steps in PBL to ensure equivalence in air-surface interactions Similarity theory does not work when vertical step is larger 100 m Requires the assumption of balance between generation and dissipation of TKE within PBL</p>
<b><i>(Mesinger et al, 1988)</i></b>		
<b><i>Theta</i></b>	<p>Potential vortex characteristics are conserved Precipitation spin up is short Increases vertical resolution in strong baroclinic areas Better describes horizontal and vertical wind shear Adiabatic vertical motions are already included in prognostic equations for horizontal wind components</p>	<p>CS and TS can cross CSs vary during a day Vertical step is not monotonic Pure resolution within thick adiabatic layer Does not allow combination with another systems</p>

***(Shapiro and Hastings, 1973)***

PBL – planetary boundary layer  
PG – pressure gradient  
CS – coordinated surface  
TS – terrain surface  
TKE – turbulent kinetic energy

## Model stages

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# PBL parameterization (numeric problems)

Level 2.5 closure (Mellor and Yamada, 1974)

**Algorithm for generation and dissipation of TKE**

$$\frac{\partial q}{\partial t} = Aq^2$$

Finite difference approximation

$$A = \left[ S_M G_M + S_H G_H - B^{-1} \right] l^{-1}$$

$$G_M = l^2 q^{-2} \left[ (\partial U / \partial z)^2 + (\partial V / \partial z)^2 \right]$$

$$G_H = -l^2 q^{-2} \beta g \partial \theta / \partial z$$

$S_M, S_H$  – moment and heat fluxes  
 $U, V$  – wind components,  
 $q$  – substance,  
 $l$  – Monin-Obukhov length,  
 $\beta, B$  – empirical constants.

$$q^{\tau+1} = q^\tau + A^\tau \Delta t \left( q^{\tau+1} \right)^2$$

Two roots

$$q_1^{\tau+1} = \left[ 1 - \left( 1 - 4 A^\tau q^\tau \Delta t \right)^{1/2} \right] \left( 2 A^\tau \Delta t \right)^{-1}$$

always > 0 – physical solution

$$q_2^{\tau+1} = \left[ 1 + \left( 1 - 4 A^\tau q^\tau \Delta t \right)^{1/2} \right] \left( 2 A^\tau \Delta t \right)^{-1}$$

can be < 0 – numerical solution

# PBL parameterization (numeric problems)

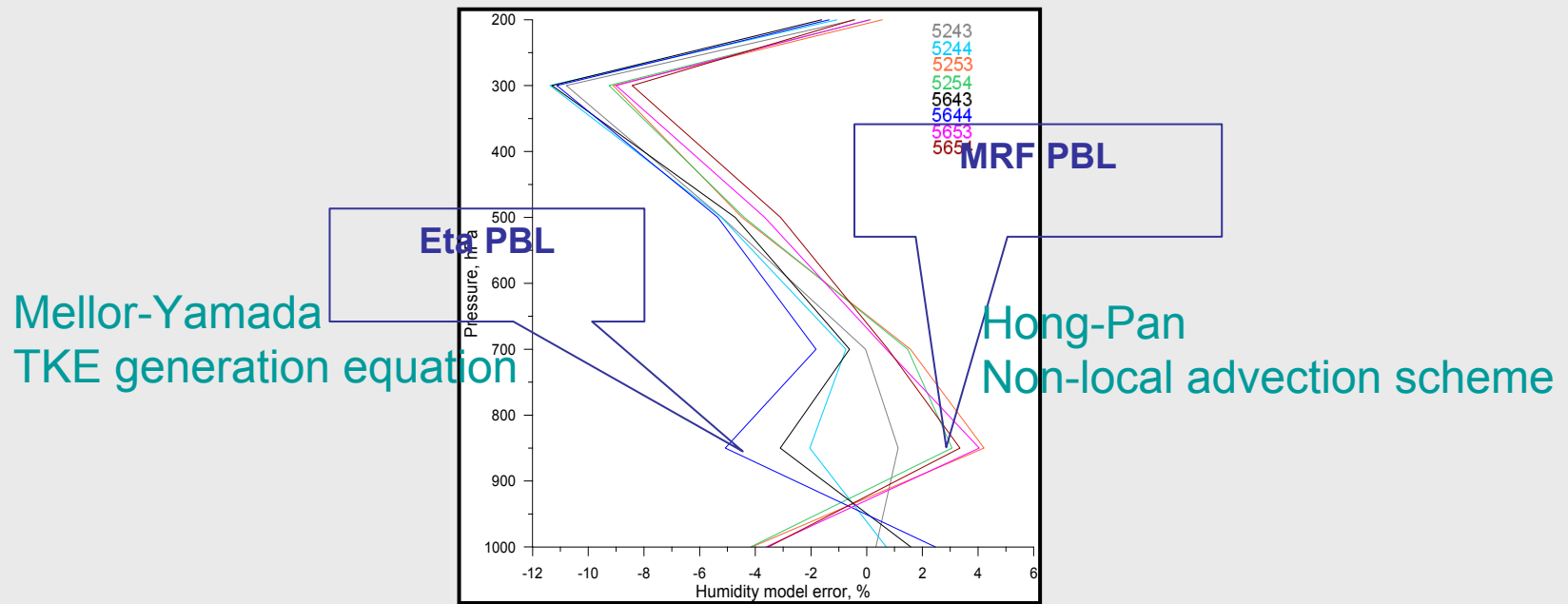
Level 2.5 closure (Mellor and Yamada, 1974)

$$Adv(v, q^2)_{(L+1/2)} = 0,5 \left[ Adv(v_L, q_{L+1/2}^2) + Adv(v_{L+1}, q_{L+1/2}^2) \right]$$

- Split numerical scheme can bring **TKE < 0**

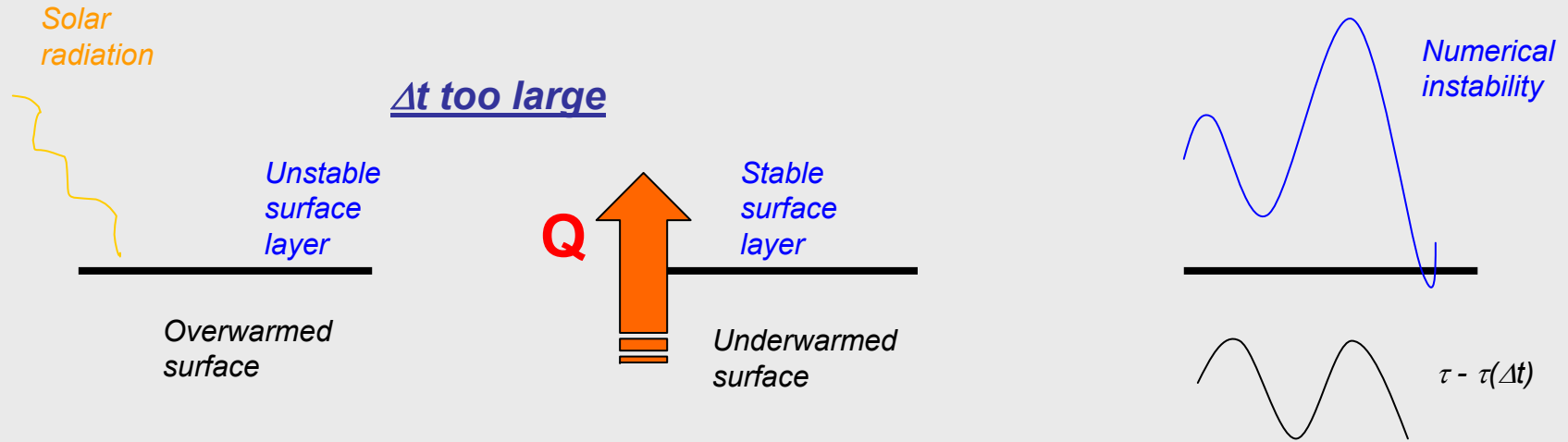
\* **TKE** → ∞ => numerical instability => restriction for TKE generation => loosing realistic description

# Sensitivity to PBL scheme

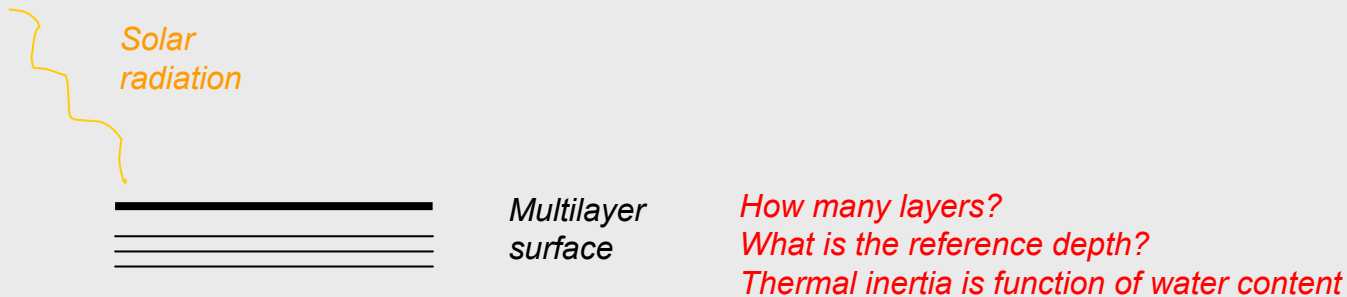


# PBL parameterization (numeric problems)

## Temperature oscillations on the surface



Уменьшение шага по времени ограничено техническими возможностями  
Фильтрация колебаний имеет формальный подход



# Microphysics parameterization (numeric problems)

Water budget scheme (Kuo, 1965; Kuo, 1974)

Assumption: convection is uniquely associated with convective precipitation and determined by large-scale convergence

$$P = (1 - b) \int_0^{top} \left( \frac{\partial \overline{\rho q}}{\partial t} \right)_h dz$$

$P$  – precipitation on surface,  
 $\rho q$  – mean water content in a layer,  
 $h$  – layer depth,  
 $b$  – Kuo parameter, which determine a part of total water converting into precipitation.

## Shortness:

Available potential energy is not taken into account => positive feedback  
convection intensification → water  
convergence intensification → convection  
intensification → ... → overestimation of  
convective precipitation while  
underestimation of stratiform (large-scale)  
precipitation

# Microphysics parameterization (numeric problems)

Adjustment schemes (*Manabe and Strickler, 1964; Betts, 1986, ...*)

Assumption: adjustment of unstable atmospheric state to the *reference* profile occurs during a certain time scale ( 1 hour for the deep convection, 3 hours for the shallow convection)

$$\left. \frac{\partial T}{\partial t} \right|_{conv} = \frac{T^{ref} - \bar{T}}{\tau} \quad \left. \frac{\partial q}{\partial t} \right|_{conv} = \frac{q^{ref} - \bar{q}}{\tau}$$

$\tau$ - convective adjustment time scale  
 $T^{ref}$  – reference temperature profile,  
 $T$  – temperature profile at the start point,  
 $q^{ref}$  – reference humidity profile,  
 $q$  - humidity profile at the start point.

**Shortness**  
*Reference profiles*



# Microphysics parameterization (numeric problems)

## Mass flux schemes (see overview by Bechtold, 2007)

(Fraedrich, 1973; Arakawa and Schubert, 1974; Bougeault, 1985; Tiedtke, 1989; Kain and Fritsch, 1990; Raymond and Blyth, 1992; Donner, 1993; Gregory et al, 1997; Gregory et al, 2000; Wang and Stevens, 2000; Bechtold et al, 2001)

Small Area Approximation  
(Wang and Stevens, 2000)

Mass flux in general is good,  
but in individual convective  
cloud is not

Entraining / detraining  
plume model (Gregory et al,  
1997)

There is no universally valid  
formulation of entrainment  
rate applicable to all  
convective simulations

Episodic mixing  
(Raymond and Blyth,  
1992)

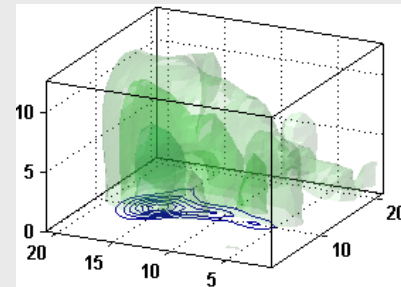
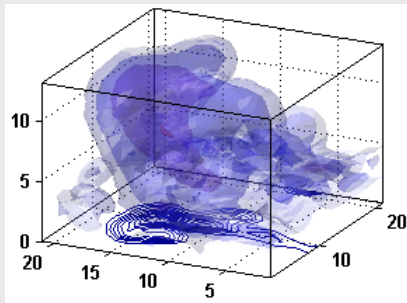
Stochastic distribution  
of mixing fraction.  
Model is very complex  
and numerically  
expensive.

# Sensitivity to microphysics parameterizations

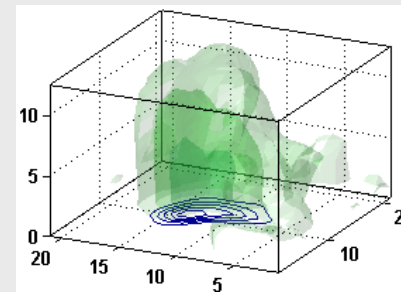
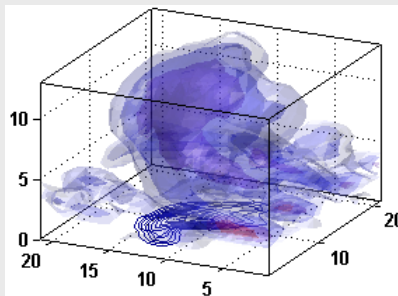
Cloud Water

Rain Water

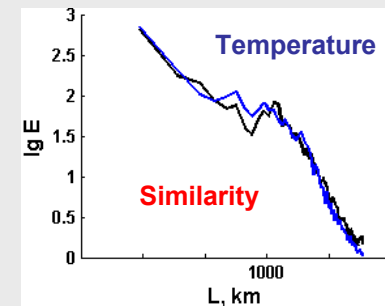
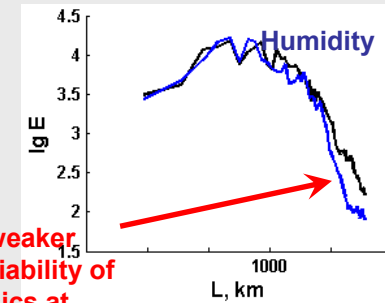
Grell  
Convection  
  
Blackadar  
PBL



Kain-Fritsch  
Convection  
  
Eta  
PBL



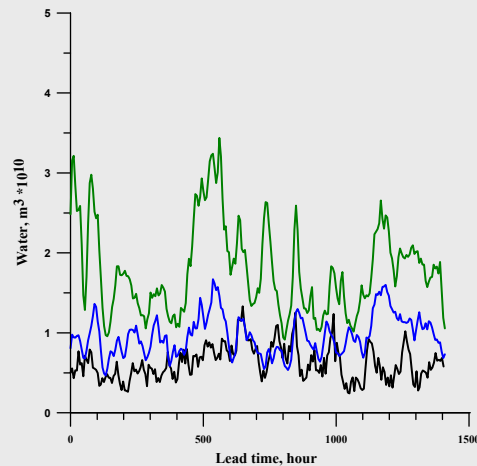
Stronger/weaker  
spatial variability of  
microphysics at  
mesoscales



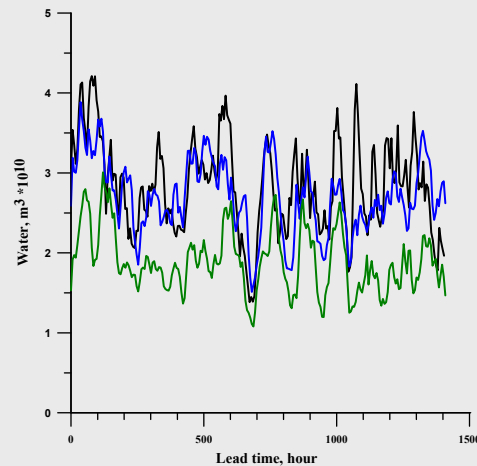
Water content in different aggregation states = Water content in different aggregation states  
Large scale patterns = Large scale patterns

(Ivanov et al, 2009)

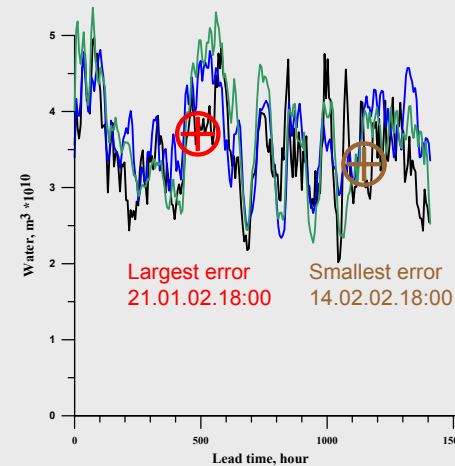
# Sensitivity to microphysics parameterizations



Convective



Large scale



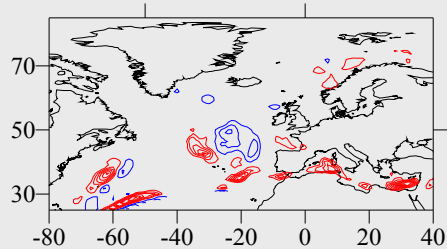
Total

ERA40  
Kain-Fritsch  
Kuo

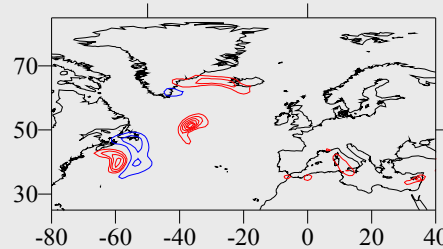
1. The total amount of precipitation over the domain is reproduced in a good agreement with the reanalysis.
2. Water in the model is redistributed between convective and large scale precipitation.
3. The Kuo scheme while providing good *dif* diagnostics for humidity, significantly overestimates convective and underestimates large scale precipitation

(Ivanov et al, 2008)

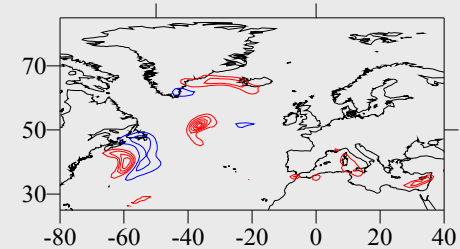
# Errors in precipitation modelling



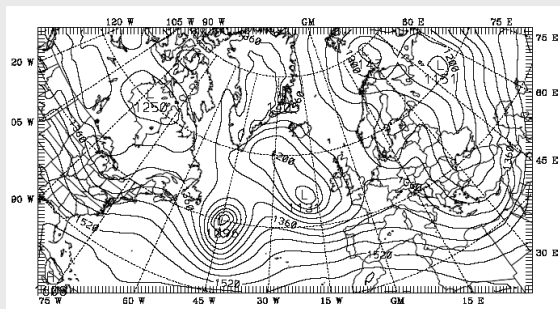
Convective



Large scale



Total



Overestimation of convective precipitation over the warm ocean.  
Phase error of large scale precipitation over an area of intensive atmosphere-ocean interaction.  
Areas of both convective and large scale precipitation errors related to two cyclonic patterns with moderate rain over the Atlantic

21 Jan 2002 18:00

*(Ivanov et al, 2008)*

**Thanks for your attention**